

Financial Econometrics

Estimation and Inference

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Outline

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- 2 Financial Econometrics – What will you learn?
 - What is financial econometrics?
 - Topics Covered
- 3 Inference and Estimation
 - Minimum Variance Unbiased Estimation
 - Consistency
- 4 Maximum Likelihood
- 5 Bayesian Inference
- 6 Summary

Who am I?

- Professor and BB&T Scholar at Clemson University
- Federal Reserve Bank of Atlanta
- Research
- Brief summary
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What is Financial Econometrics?

- Financial econometrics is the use of econometric procedures to answer financial questions using financial data
- What sorts of questions?
- Statistical analysis to inform an economic analysis
 - ▶ What factors affect stock returns and how much do they do so?
 - ▶ Interest rates on Irish government debt have fallen substantially. Are they likely to go up or down?
 - ▶ How likely is it that a portfolio will lose 20 percent of its value in any given 12-month period?
 - ▶ Are stock prices mean reverting? Are stock returns mean reverting?
 - ▶ Is the value of the euro likely to go up or down? What does it depend on?
 - ▶ The Swiss franc has risen a lot in the last week and there are widespread losses. Who is losing and why did they have the trades on that they had?
- Mostly time series data

Topics covered

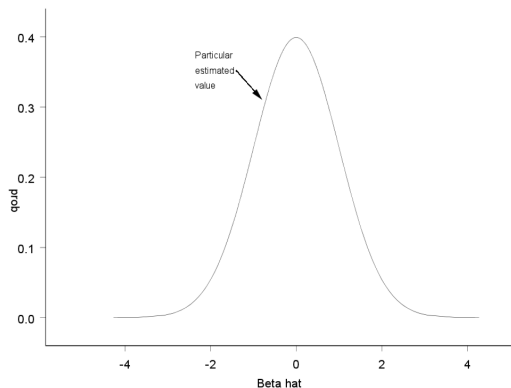
- Estimation
- Summarizing data and behavior of returns
- Event studies
- Univariate time series
- Multivariate time series (Vector autoregressions)
- Multivariate time series (Error correction mechanisms)
- Volatility
- Multivariate volatility
- Nonlinear time series analysis
- Value at risk

Topics covered and text

- Brooks, Chs. 1 and 2 - Estimation and Summarizing data and behavior of returns
- Class slides and Campbell, Lo and MacKinley Ch. 4, Event studies
- Brooks, Ch. 5 - Univariate time series
- Brooks, Ch. 6 - Multivariate time series (Vector autoregressions)
- Brooks, Ch. 7 - Multivariate time series (Error correction mechanisms)
- Brooks, Ch. 8 - Volatility and Multivariate volatility
- Brooks, Ch. 9 - Nonlinear time series analysis
- Riskmetrics Brochure - Value at risk

Purpose of inference

- What are plausible and implausible values of estimates of a particular parameter?
 - ▶ Point estimate



Criteria for estimators

- Classical statistics
 - ▶ Minimum Variance Unbiased Estimators (MVUE)
 - ★ or Best Linear Unbiased Estimator (BLUE)
 - ★ or Ordinary Least Squares (OLS)
 - ▶ Maximum likelihood
 - ★ Conditional on the data, pick the most likely value

OLS

- Ordinary least squares with x fixed (nonstochastic)
- Suppose that x is not stochastic
 - ▶ x is deterministic, fixed in repeated samples
 - ▶ e.g. treatments of crops on plots
 - ▶ time trend
 - ▶ quarterly dummy variables

$$y_i = x_i\beta + \varepsilon_i, \quad i = 1, \dots, N$$

$$E y_i = E x_i = 0$$

$$E \varepsilon_i = 0, \quad E \varepsilon_i^2 = \sigma^2, \quad E \varepsilon_i \varepsilon_j = 0 \quad \forall i \neq j$$

OLS with nonstochastic regressors is unbiased

- Properties of equation

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- $\hat{\beta}$ can be written

$$\begin{aligned}\hat{\beta} &= \frac{\sum xy}{\sum x^2} \\ &= \frac{\sum xx\beta}{\sum x^2} + \frac{\sum x\varepsilon}{\sum x^2} \\ &= \beta + \frac{\sum x\varepsilon}{\sum x^2}\end{aligned}$$

OLS with nonstochastic regressors is unbiased

- And the expected value of $\hat{\beta}$ is

$$\begin{aligned} E\hat{\beta} &= E\beta + E\frac{\sum x\varepsilon}{\sum x^2} \\ &= \beta + \frac{\sum x E\varepsilon}{\sum x^2} \\ &= \beta \end{aligned}$$

Why x nonstochastic?

- Consider the term $E \frac{\sum x\varepsilon}{\sum x^2}$ in $E \hat{\beta} = \beta + E \frac{\sum x\varepsilon}{\sum x^2}$
- If x is not random, then

$$E \frac{\sum x\varepsilon}{\sum x^2} = \frac{\sum x E \varepsilon}{\sum x^2}$$

- If x is random, then in general

$$E \frac{\sum x\varepsilon}{\sum x^2} \neq \frac{E \sum x\varepsilon}{E \sum x^2}$$

Why unbiased if x nonstochastic?

- Expectations operator is a linear operator
- If a is a constant, then

$$E ax = a E x$$

- If $\frac{x}{\sum x^2}$ is a constant, then

$$E \frac{x\varepsilon}{\sum x^2} = \frac{x}{\sum x^2} E \varepsilon$$

- In general,

$$E \frac{x\varepsilon}{\sum x^2} \neq \frac{E(x\varepsilon)}{E \sum x^2} \text{ and } E \frac{x\varepsilon}{\sum x^2} \neq E \left[\frac{x}{\sum x^2} \right] E \varepsilon$$

Right-hand side variable (x) stochastic and least squares works

- The case with x stochastic in which least squares works: x and ε are independent

$$E \frac{x\varepsilon}{\sum x^2} = E [f(x) \varepsilon] \text{ with } f(x) = \frac{x}{\sum x^2}$$

$$E [f(x) \varepsilon] = E f(x) E \varepsilon \text{ if } x \text{ and } \varepsilon \text{ are independent}$$

$$E f(x) E \varepsilon = 0 \text{ because } E \varepsilon = 0$$

- If x and ε are normally distributed and uncorrelated, then least squares is unbiased
 - ▶ Sufficient but not necessary

OLS is MVUE and BLUE

- MVUE: $\text{Var} [\hat{\beta}]$ around true value is a minimum among estimators that are unbiased
- BLUE: $\hat{\beta}$ is a linear function of the y_i , is unbiased and has minimum variance among unbiased estimators
 - ▶ Estimator is a linear function of the y_i because

$$\hat{\beta} = \frac{\sum x_i y_i}{\sum x_i^2} = \sum w_i y_i, \quad w_i = \frac{x_i}{\sum x_i^2}$$

Unbiasedness in a time series setting

- Unbiasedness will hardly come up in this class
- Why?
- Time series regression with dependence on past values
 - ▶ $y_t = \beta y_{t-1} + \varepsilon_t, \quad t = 1, \dots, T$
 - ★ Assume that y_{t-1} and ε_t are independent
 - ★ Correlation of y_{t-1} and ε_t is zero
 - ★ Implies that $E y_{t-1} \varepsilon_t = 0$
- An ordered sequence of observations from 1 to T
- This is called a first-order autoregression
 - ▶ y_0
 - ▶ \downarrow
 - ▶ $y_1 \leftarrow \varepsilon_1$

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 - ▶ \downarrow
 - ▶ $y_1 \leftarrow \varepsilon_1$
 - ▶ \downarrow
 - ▶ $y_2 \leftarrow \varepsilon_2$
 - ▶ ...

OLS an unbiased estimator?

- Ordinary Least Squares (OLS) estimator for an autoregression?

$$\begin{aligned}\hat{\beta} &= \frac{\sum y_t y_{t-1}}{\sum y_{t-1}^2} \\ &= \frac{\sum \beta y_{t-1} y_{t-1}}{\sum y_{t-1}^2} + \frac{\sum \varepsilon_t y_{t-1}}{\sum y_{t-1}^2} \\ &= \beta + \frac{\sum \varepsilon_t y_{t-1}}{\sum y_{t-1}^2}\end{aligned}$$

- y_{t-1} not fixed in repeated samples
 - ▶ Can't have different ε_t and same set of y 's $\forall t = 1, \dots, T$
 - ▶ For example, a different ε_2 implies a different y_2 and a different y_2 implies a different y_3 , and so on
- So y_{t-1} must be stochastic

OLS an unbiased estimator?

- Just because y_{t-1} is stochastic doesn't mean that OLS is not unbiased

$$\hat{\beta} = \beta + \frac{\sum \varepsilon_t y_{t-1}}{\sum y_{t-1}^2}$$

- Seems like y_{t-1} and ε_t are independent and they are
 - ▶ By assumption, ε_t is independent of y_{t-1}
- But y_t depends on ε_t , and so does y_{t+1} , y_{t+2} , etc.

$$\begin{aligned} E \hat{\beta} &= \beta + E \frac{\sum \varepsilon_t y_{t-1}}{\sum y_{t-1}^2} \\ &= \beta + \sum E \left[\left(\frac{y_{t-1}}{\sum y_{t-1}^2} \right) \varepsilon_t \right] \end{aligned}$$

- ε_t and $\sum_{t=1}^T y_{t-1}^2$ cannot be independent and $\hat{\beta}$ is not an unbiased estimator in general

Digression: Least squares and error term

- One way to see why $E \sum x\varepsilon = 0$ is required for unbiasedness:
- What is the correlation of the error term and right-hand-side variables in a computed regression? The covariance of x and the computed error term is identically zero (for any correct program)

Unbiasedness in a time series context

- In general, estimators are not unbiased in a time series context because they're part of a sequence
- Will focus on consistency

Bottom line on asymptotics and time series

- Consistency is more pertinent than unbiasedness
- The limiting distribution provides a way to estimate the variability of the estimator
 - ▶ Some algebra can show that the mean \bar{y}_T of a normally distributed variable has the asymptotic distribution $N(\mu, \sigma^2 / T)$
 - ▶ This is the same as the finite-sample distribution in this case, but the asymptotic distribution often is easier to find

Simple problem of estimating the mean of a normally distributed variable

- In general, estimators are not unbiased in a time series context because they're part of a sequence but they can be unbiased if dependence over time is unimportant
- Suppose y is normally distributed

$$y \sim N(\mu, \sigma^2) \text{ or can be written } y \sim \text{NIND}(\mu, \sigma^2)$$

- By definition

$$\bar{y}_T = \frac{\sum y_t}{T} \text{ and } s_T^2 = \frac{\sum (y_t - \bar{y})^2}{T-1}$$

- It's shown in basic statistics that

$$E \bar{y}_T = \mu \text{ and } E s_T^2 = \sigma^2$$

- Also

$$\begin{aligned} \text{Var}[\bar{y}_T] &= \frac{\text{Var}[\sum y_t]}{T^2} = T^{-2} \sum \text{Var}[y_t] \\ &= \frac{\sum \sigma^2}{T^2} = \frac{T\sigma^2}{T^2} = \frac{\sigma^2}{T} \end{aligned}$$

Definition of convergence in probability

- Let θ_T be an estimator with sample size T and θ a parameter with some particular value
- Definition: θ_T **converges in probability** to a constant θ if
$$\lim_{T \rightarrow \infty} \Pr(|\theta_T - \theta| > \epsilon) = 0 \quad \forall \epsilon > 0$$
 - ▶ ϵ is “some constant value”, not an error term
- Write $\text{plim } \theta_T = \theta$

Example of consistent estimator

- Suppose that $\theta = 0$ and θ_T is an estimator that takes on the values 0 and T

$$\Pr(\theta_T = 0) = 1 - \frac{1}{T} \text{ and } \Pr(\theta_T = T) = \frac{1}{T}$$

- Therefore

$$\lim_{T \rightarrow \infty} \Pr(\theta_T = T) = 0$$

$$\lim_{T \rightarrow \infty} \Pr(\theta_T = 0) = 1$$

- Because $\theta = 0$,

$$\lim_{T \rightarrow \infty} \Pr(|\theta_T - \theta| > \epsilon) = 0 \quad \forall \epsilon > 0$$

- and

$$\lim_{T \rightarrow \infty} \Pr(|\theta_T - \theta| < \epsilon) = 1 \quad \forall \epsilon > 0$$

- and therefore

$$\text{plim } \theta_T = \theta$$

- If θ equalled something other than zero, then θ_T is an inconsistent estimator of θ

Properties of probability limits

- Suppose we have estimates a_T of a parameter α and b_T of a parameter β
- Suppose that $\text{plim } a_T = \alpha$ and $\text{plim } b_T = \beta$
- Then

$$\text{plim } (a_T + b_T) = \text{plim } a_T + \text{plim } b_T = \alpha + \beta$$

$$\text{plim } (a_T b_T) = \text{plim } a_T \text{plim } b_T = \alpha\beta$$

$$\text{plim } (a_T / b_T) = \text{plim } a_T / \text{plim } b_T = \alpha / \beta \text{ if } \beta \neq 0$$

- This can be contrasted with the expectation operator for which, in general,

$$E a_T b_T \neq \alpha\beta$$

$$E a_T / b_T \neq \alpha / \beta$$

Convergence in distribution

- Want nondegenerate distribution of estimator
 - ▶ If an estimator θ_T is a consistent estimator of θ , then estimator converges to a constant
 - ▶ We want some measure of the variability of the estimator
 - ▶ This is where the asymptotic distribution comes in
- The **asymptotic distribution** of an estimator is a distribution that is used to approximate the finite-sample distribution of the estimator
- Some function of the estimator converges to a distribution, the asymptotic distribution

Limiting Distribution

- Definition: If θ_T converges in distribution to the random variable θ , where $F(\theta)$ is the cumulative distribution function of θ , then $F(\theta)$ is the **limiting distribution** of θ_T

- Often written

$$\theta_T \rightarrow^d F(\theta)$$

- If $F(\theta)$ is a common form such as $N(\mu, \sigma^2/T)$, this is often written as

$$\theta_T \rightarrow^d N(\mu, \sigma^2/T)$$

- ▶ Proved by showing, for example, that $\sqrt{T}\theta_T$ converges to $N(\mu, \sigma^2)$

Bottom line on asymptotics and time series

- Consistency is more pertinent than unbiasedness
- The limiting distribution provides a way to estimate the variability of the estimator
 - ▶ Some algebra can show that the mean \bar{y}_T of a normally distributed variable has the asymptotic distribution $N(\mu, \sigma^2 / T)$
 - ▶ This is the same as the finite-sample distribution in this case, but the asymptotic distribution often is easier to find

Maximum likelihood estimation is commonly invoked to justify an estimator

- Maximum likelihood often is a convenient way to obtain a consistent estimator
- Maximum likelihood uses the distribution of the observations
- Maximum likelihood obtains point estimates of the parameters as the ones most likely to have generated the observations
- Maximum likelihood provides a relatively straightforward way of estimating the variance of parameters

Maximum likelihood estimation of the parameters of a normal distribution

- Have a sample of T observations, y_1, y_2, \dots, y_T
- Suppose they are generated independently from a normal distribution with mean μ and variance σ^2
- Each observation has the distribution

$$\frac{1}{\sigma (2\pi)^{1/2}} \exp \left[-\frac{1}{2\sigma^2} (y_t - \mu)^2 \right]$$

- The joint sample of T observations has the distribution

$$f(y_t | \mu, \sigma^2) = \frac{1}{\sigma^T (2\pi)^{T/2}} \exp \left[-\frac{1}{2\sigma^2} \sum_{t=1}^T (y_t - \mu)^2 \right]$$

- The likelihood function of these data and parameters is

$$L(\mu, \sigma^2 | y_t) = \frac{1}{\sigma^T (2\pi)^{T/2}} \exp \left[-\frac{1}{2\sigma^2} \sum_{t=1}^T (y_t - \mu)^2 \right]$$

The log of the likelihood function

- The likelihood function of the parameters for a normal distribution is

$$L(\mu, \sigma^2 | y_t) = \frac{1}{\sigma^T (2\pi)^{T/2}} \exp \left[-\frac{1}{2\sigma^2} \sum_{t=1}^T (y_t - \mu)^2 \right]$$

- The log of the likelihood often is more convenient for exponential distributions such as the normal distribution

$$\ln L(\mu, \sigma^2 | y_t) = -\frac{T}{2} 2\pi - T \ln \sigma - \frac{1}{2\sigma^2} \sum_{t=1}^T (y_t - \mu)^2$$

Maximum likelihood estimation of mean and variance

- The log of the likelihood function

$$\ln L(\mu, \sigma^2 | y_t) = -\frac{T}{2} \ln 2\pi - T \ln \sigma - \frac{1}{2\sigma^2} \sum_{t=1}^T (y_t - \mu)^2$$

- Maximize likelihood as a function of parameters conditional on the data
 - ▶ Can do all at once or sequentially
- Want to estimate μ
- Denote the estimator by a “hat” over it
- Maximize by solving

$$\frac{\partial \ln L}{\partial \mu} = \frac{1}{\sigma^2} \sum_{t=1}^T (y_t - \hat{\mu}) = 0$$

Maximum likelihood estimation of mean and variance

- Maximize by solving

$$\frac{\partial \ln L}{\partial \mu} = \frac{1}{\sigma^2} \sum_{t=1}^T (y_t - \hat{\mu}) = 0$$

$$\sum_{t=1}^T (y_t - \hat{\mu}) = 0$$

$$\sum_{t=1}^T y_t = T \hat{\mu}$$

$$\hat{\mu} = \frac{\sum_{t=1}^T y_t}{T} = \bar{y}$$

Illustration

- Likelihood function

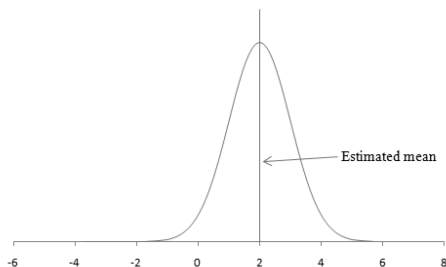


Figure: Likelihood function of normally distributed data with mean \bar{y} of 2 and variance $s_{ml}^2 = \sum (y - \bar{y})^2 / T$ of 1. The maximum likelihood estimator is the mean of the normal distribution.

Finish by finding estimator of variance

- Estimator of σ^2
- Concentrate μ out of likelihood function by replacing it by \bar{y}

$$\begin{aligned}\ln L(\sigma^2 | y_t) &= -\frac{T}{2} \ln 2\pi - T \ln \sigma - \frac{1}{2\sigma^2} \sum_{t=1}^T (y_t - \hat{\mu})^2 \\ &= -\frac{T}{2} \ln 2\pi - \frac{T}{2} \ln \sigma^2 - \frac{1}{2\sigma^2} \sum_{t=1}^T (y_t - \bar{y})^2\end{aligned}$$

- Maximize the concentrated likelihood function with respect to σ^2

Finish by finding estimator of variance

- Maximize likelihood function with respect to σ^2

$$\ln L(\sigma^2 | y_t) = -\frac{T}{2} \ln 2\pi - \frac{T}{2} \ln \sigma^2 - \frac{1}{2\sigma^2} \sum_{t=1}^T (y_t - \bar{y})^2$$

- Solve

$$\frac{\partial \ln L}{\partial \sigma^2} = -\frac{T}{2} \frac{1}{\hat{\sigma}^2} + \frac{1}{2} \frac{1}{\hat{\sigma}^4} \sum_{t=1}^T (y_t - \bar{y})^2 = 0$$

$$-T + \frac{1}{\hat{\sigma}^2} \sum_{t=1}^T (y_t - \bar{y})^2 = 0$$

$$\hat{\sigma}^2 = \frac{\sum_{t=1}^T (y_t - \bar{y})^2}{T}$$

Consistency and unbiasedness

- $\hat{\mu} = \bar{y}$ and $\hat{\sigma}^2 = \frac{\sum_{t=1}^T (y_t - \bar{y})^2}{T}$ are consistent estimators of μ and σ^2
 - ▶ Not necessarily unbiased
 - ▶ $\hat{\sigma}^2 = \frac{\sum_{t=1}^T (y_t - \bar{y})^2}{T}$ is a biased estimator of σ^2
 - ★ Not very important with enough observations

Properties of maximum likelihood estimators commonly mentioned

- Maximum likelihood provides a couple of natural estimators of the variance of the estimator
- Let θ be a parameter we have estimated

$$\text{Var} [\hat{\theta}] \geq \left(\text{E} [(\partial \ln L(\theta|y) / \partial \theta)]^2 \right)^{-1}$$

where the expectation with respect to the distribution of y 's is evaluated at the true parameter

- Under regularity conditions

$$\text{E} [(\partial \ln L(\theta|y) / \partial \theta)]^2 = - \text{E} \left[\frac{\partial^2 \ln L(\theta|y)}{\partial \theta^2} \right]$$

- The term information matrix denotes

$$I = - \text{E} \left[\frac{\partial^2 \ln L(\theta|y)}{\partial \theta^2} \right]$$

- Therefore, under regularity conditions,

$$\text{Var} [\hat{\theta}] = I^{-1}$$

Typical properties of maximum likelihood estimators

- Let $\hat{\theta}_{ML}$ be the maximum likelihood of some estimator
 - ▶ Suppose that the likelihood function has a single peak and a unique maximum
- Fairly general properties
 - ▶ $\text{plim } \hat{\theta}_{ML} = \theta$
 - ▶ $\hat{\theta}_{ML} \rightarrow^d N(\theta, I^{-1})$
 - ▶ Asymptotic variance of $\hat{\theta}_{ML}$ is $A\text{Var}(\hat{\theta}_{ML}) = I^{-1}$
 - ▶ Asymptotic standard deviation of $\hat{\theta}_{ML}$ is $\text{ASD}(\hat{\theta}_{ML})$
 - ▶ t-ratio is $\frac{\hat{\theta}_{ML} - \theta}{\text{ASD}(\hat{\theta}_{ML})} \sim N(0, 1)$
 - ▶ Can do more complicated tests by likelihood ratio test
 - ▶ $-2 \ln \left(\frac{\max \text{Likelihood Restricted}}{\max \text{Likelihood Unrestricted}} \right) \sim \chi^2$ (degrees of freedom = number of restrictions)

Bayes rule

- Foundation is Bayes rule
- Combine likelihood function of parameters with prior information to get posterior distribution and conclusions
 - ▶ Prior – before the data
 - ▶ Posterior – after the data

Bayes rule is simple

- The application is the big jump
- Start from definition of conditional probability

$$\text{pr}(A, B) = \text{pr}(A|B) \text{pr}(B)$$

- ▶ where $\text{pr}(A, B)$ is the joint probability of two events A and B
- ▶ $\text{pr}(A|B)$ is the probability of the event A conditional on the event B
- ▶ $\text{pr}(B)$ is the probability of B
- This equation defines conditional probability

$$\text{pr}(A|B) = \text{pr}(A, B) / \text{pr}(B) \text{ if } \text{pr}(B) \neq 0$$

- Also can say

$$\text{pr}(A, B) = \text{pr}(B|A) \text{pr}(A)$$

- Equate two definitions and get

$$\text{pr}(B|A) = \frac{\text{pr}(A|B) \text{pr}(B)}{\text{pr}(A)}$$

Bayesian interpretation

$$\text{pr}(B|A) = \frac{\text{pr}(A|B) \text{pr}(B)}{\text{pr}(A)}$$

- Want to draw an inference about probability of observing event B
 - ▶ Observe some discrete event A
 - ▶ $\text{pr}(B|A)$ is the probability of B conditional on observing A
 - ▶ $\text{pr}(B)$ is prior probability that B is true
 - ▶ $\text{pr}(A|B)$ is probability of observing A if B is true
 - ▶ $\text{pr}(A)$ is the probability of observing A whether B is true or not
 - ▶ Note that $\text{pr}(A)$ is the unconditional probability of observing A
 - ★ $\text{pr}(A) = \text{pr}(A|B) \text{pr}(B) + \text{pr}(A|\text{not } B) \text{pr}(\text{not } B)$

$$\text{pr}(B|A) = \frac{\text{pr}(A|B) \text{pr}(B)}{\text{pr}(A|B) \text{pr}(B) + \text{pr}(A|\text{not } B) \text{pr}(\text{not } B)}$$

Example of Bayesian analysis

$$\text{pr}(B|A) = \frac{\text{pr}(A|B) \text{pr}(B)}{\text{pr}(A|B) \text{pr}(B) + \text{pr}(A|\text{not } B) \text{pr}(\text{not } B)}$$

- Example: B is the result that have illness, say flu
 - ▶ A is some evaluation
 - ▶ Have a prior probability of having flu, $\text{pr}(B)$, say 50 percent
 - ▶ How informative is it if you go to doctor's office and he says you have the flu?
 - ▶ Suppose doctor says you have the flu
 - ★ 80 percent of time when you do $\text{pr}(A|B)$
 - ★ 20 percent when you don't $\text{pr}(A|\text{not } B)$
 - ▶ If the doctor says you have the flu, then the probability of your having the flu is
$$\frac{.8 \cdot .5}{.8 \cdot .5 + .2 \cdot .5} = \frac{.40}{.50} = .80$$
 - ▶ A lot of information in the doctor's evaluation

Second example of Bayesian analysis

$$\text{pr}(B|A) = \frac{\text{pr}(A|B) \text{pr}(B)}{\text{pr}(A|B) \text{pr}(B) + \text{pr}(A|\text{not } B) \text{pr}(\text{not } B)}$$

- Have a prior probability of having flu, $\text{pr}(B)$, say 50 percent
- Go to doctor's office and he says you have the flu
- Suppose that he says you have the flu
 - ▶ 60 percent of time when you do $\text{pr}(A|B)$
 - ▶ 40 percent when you don't $\text{pr}(A|\text{not } B)$
- Then the probability of your having the flu given the doctor says you do is

$$\frac{.6 \cdot .5}{.6 \cdot .5 + .4 \cdot .5} = \frac{.30}{.50} = .60$$

- If $\text{pr}(A|B)$ and $\text{pr}(A|\text{not } B)$ are both 0.5, then $\text{pr}(B|A) = .5$, the prior probability

Diffuse prior

- First example
 - ▶ prior probability of flu is .5
 - ▶ probability that doctor will say you have the flu is .8 if you do
 - ▶ posterior probability is .8
- Second example
 - ▶ prior probability of flu is .5
 - ▶ probability that doctor will say you have the flu is .6 if you do
 - ▶ posterior probability is .6
- You had a diffuse prior – equal probabilities of flu or not – and you learned what can be learned from doctor

Third example of Bayesian analysis

$$\text{pr}(B|A) = \frac{\text{pr}(A|B) \text{pr}(B)}{\text{pr}(A|B) \text{pr}(B) + \text{pr}(A|\text{not } B) \text{pr}(\text{not } B)}$$

- Have a prior probability of having flu, $\text{pr}(B)$, say 80 percent
- Go to doctor's office and he says you have the flu
- Suppose that he says you have the flu
 - ▶ 80 percent of time when you do $\text{pr}(A|B)$
 - ▶ 20 percent when you don't $\text{pr}(A|\text{not } B)$
- Then the probability of your having the flu given the doctor says you do is

$$\frac{.8 \cdot .8}{.8 \cdot .8 + .2 \cdot .2} = \frac{.64}{.68} = .94$$

Analysis in econometric context

- $\text{pr}(B|A) = \frac{\text{pr}(A|B)\text{pr}(B)}{\text{pr}(A)}$
- Can write this in terms of discrete or continuous probability distribution functions
 - ▶ Let B be a parameter β and $\text{pr}(B) \equiv p(\beta)$
 - ★ Might be CAPM parameter
 - ▶ Prior probability distribution of plausible values of β for some firm
 - ▶ Let A be some data we observe and $\text{pr}(A|B) = p(y|\beta)$, the probability of the data given β

Bayesian analysis of parameter values



$$p(\beta|y) = \frac{L(\beta|y) p(\beta)}{p(y)}$$

where $p(\beta|y)$ is the posterior probability distribution of values of β conditional on the data

- $p(y)$ is a normalizing constant independent of β so this can be analyzed using

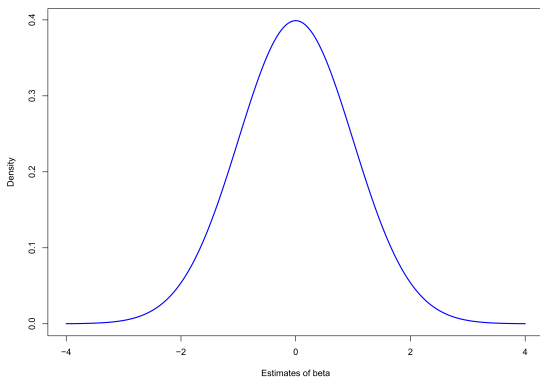
$$p(\beta|y) \propto L(\beta|y) p(\beta)$$

where \propto means “proportional to”

- Purpose is to make inferences about the posterior distribution of parameter values
 - ▶ Very flexible
 - ▶ Coherent
 - ▶ Can be computationally demanding but computer time is cheap

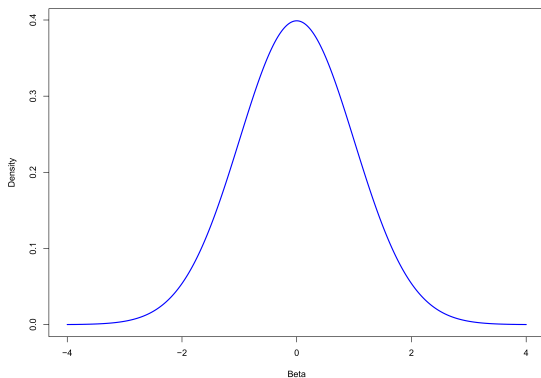
Comparison of classical and Bayesian analysis

- Classical: Probability distribution of estimator $\hat{\beta}$
 - ▶ True value is a number, zero in this case if the estimator is unbiased



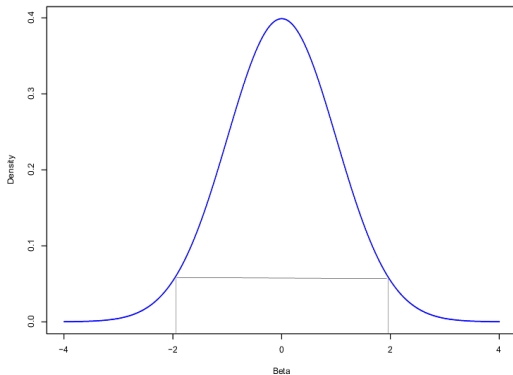
Comparison of classical and Bayesian analysis

- Bayesian: Posterior probability distribution of various possible values of β
 - ▶ True value is one of these possible values, with some more probable than others



Interpretation of Estimate of Variability

- Estimate of five percent confidence interval for a normal distribution



Summary

- Estimation issues
 - ▶ Unbiased
 - ▶ Estimate of variability
 - ▶ Consistency
 - ▶ Maximum likelihood estimator
- Bayesian statistics
 - ▶ Plausibility of posterior value after seeing data
 - ▶ Natural interpretation of variability